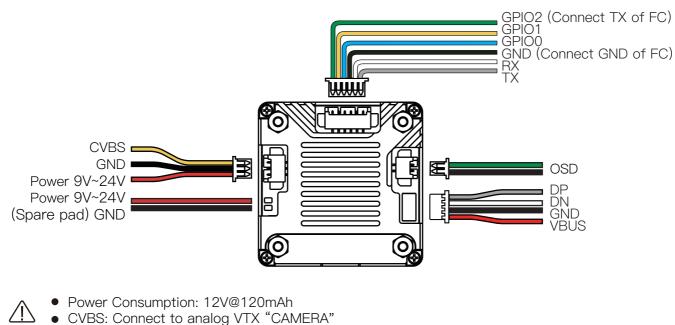
FT652 **Quick Start Guide**

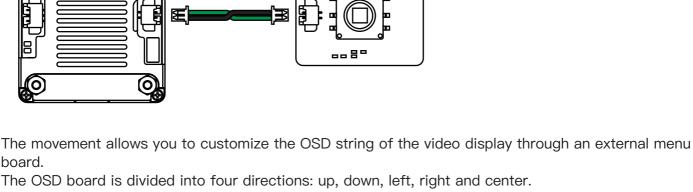


Connection



OSD Functions

port or "CVBS IN" port



Operating Instructions: 1. Connect the menu board to the movement

2. Wait for the movement to power on the picture 3. Press the center button, the operation interface will pop up, the operation interface is divided into

four lines, the first line and the second line is to provide a choice of characters, the third line is to

- delete the option, the fourth line is the current character, the black background is the current cursor position
- 4. Press up, down, left or right to move the cursor in the character line, and press center to select the character to be inserted into the current string. 5. move the cursor to DEL, press the center, you can delete the last character in the string, all clear the current string will become [NA], this time that there is no character
- 6. Move the cursor to the fourth line of the current character line, press the center key to exit the operation. This is the string if not empty, the lower left corner will have the current settings string
- **Serial Communication Description**

RX Master receive, 3.3V level, baud rate default 115200bps

version

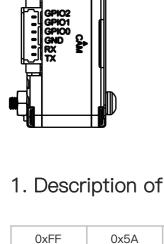
(1Byte)

header (10Byte)

cmd

(2Byte)

TX



(1Byte)

GND	Reference Ground			
GPIO0	General Purpose IO, 3.3V level			
GPIO1	General Purpose IO, 3.3V level			
GPIO2	General Purpose IO, 3.3V level			
Agreement				

payload_len

(4Byte)

payload

crc16

(2Byte)

Master transmit, 3.3V level, baud rate default 115200bps

version: Protocol version (initial version 0)

(1Byte)

1.1 Field Description		
0xFF: constant value		

sub_cmd

(1Byte)

crc16: Checksum value with header and payload

crc ^= *data++; for (i = 0; i < 8; ++i)

if (crc & 1)

payload: Data content

sub_cmd: subcommand

0x5A: constant value

cmd: Command id

1.2 Calibration Function crc16_code static uint16_t crc16_modbus(uint8_t *data, uint32_t length)

payload_len: Payload data length

uint8_t i; uint16_t crc = 0xffff; // Initial value while(length--)

```
else
           crc = (crc >> 1);
  return crc;
2. Command Definition
host→dev: The host computer sends to the device
dev→host: The device sends to the host computer
2.1 Getting the Version
                                  payload_len
(Byte)
                       sub_cmd
```

// crc ^= *data; data++;

 $crc = (crc >> 1) ^ 0xA001; // 0xA001 = reverse 0x8005$

0

Ν

Instruction

Returns the firmware

version string

Instruction

1Byte brightness value (0–100), no payload without setting only return the actual brightness value

Returns the current brightness value

1Byte contrast value (0-100), no payload

not set only return the actual contrast value

Returns the current contrast value

Instruction

Manual shutter calibration image

Disable automatic shutter calibration

Enable automatic shutter calibration

Instruction

Close Hot Tracking

FF 5A 00 01 00 00 01 00 00 00 50 EA A2

FF 5A 00 01 00 00 01 00 00 00 32 6B 4B

FF 5A 00 02 00 00 01 00 00 00 05 6A 88

FF 5A 00 02 00 00 01 00 00 00 00 AA 8B

16.5 V

Directional cmd sub_cmd host->dev 1 0

1

1

1

0

1

1

2.2 Image Adjustment

cmd

0

0

0

0

payload_len

(Byte)

1/0

1

1/0

1

Directional

host->dev

dev->host

dev->host

host->dev

dev->host

2.3 Pseudo-Color								
Directional	cmd	sub_cmd	payload_len (Byte)	Instruction				
host->dev	2	0	1	Set the pseudo-color serial number, 0 is off pseudo-color				
2.4 Shutte	r Co	ntrol						
Directional	amad	aub amd	payload_len	Instruction				

(Byte)

1

1

1

payload_len

(Byte)

1

2.5 Hot Tracking Directional cmd sub_cmd

Directional cmd sub_cmd

3

3

3

4

0

1

0

host->dev

host->dev

host->dev

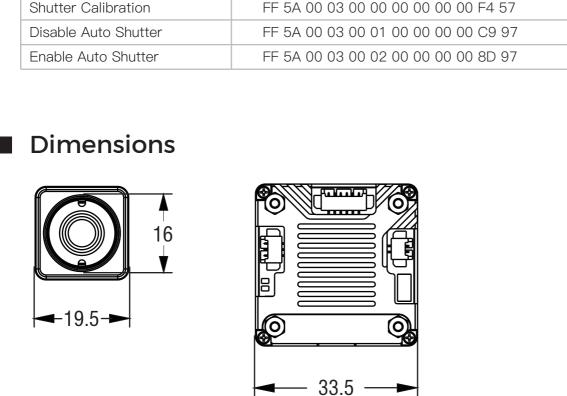
host->dev

	host->dev	4	1	1	Open Hot Tracking				
	3. Example of Command								
					0				
	Command Description Get version		Command Data						
			FF 5A 00 00 00 00 00 00 00 C7 57						
	Set the contra	ast to	80%	FF 5A 00	01 00 01 01 00 00 00 50 EB 73				
	Set the contra	ast to	50%	FF 5A 00	01 00 01 01 00 00 00 32 6A 9A				

Set pseudo color 5 Set pseudo color 0

Set the brightness to 80%

Set the brightness to 50%



Unit: mm

Specifications Model

Sensor Resolution

LENS FOV

IFOV

-20→

Frame Rate **Power Consumption** Output Supply Voltage Temperature Interface Latency Image Quality

50°(H)*37.2°(V)*62.3°(D) 3.43 50fps <1.5w PAL 9V~24V -20°C~60°C Analog Interface: CVBS Average Latency 20ms Allmage Enhancement

Uncooled Vanadium Oxide

25.5

FT652

256x192 F1.0/4mm