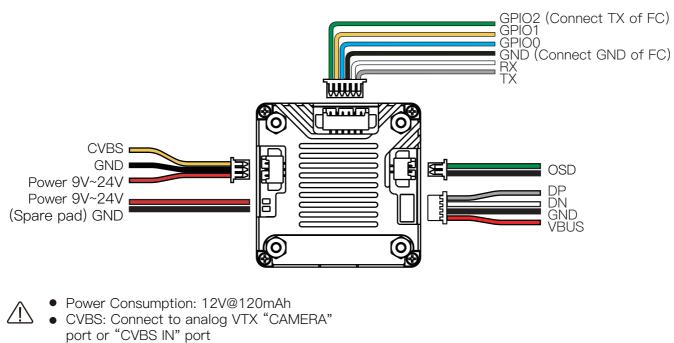
FT483

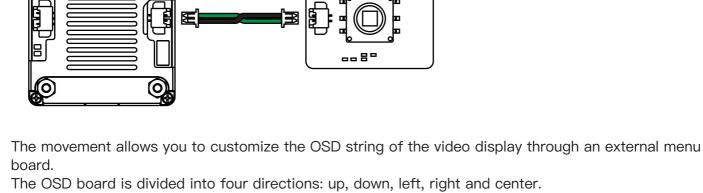
Quick Start Guide

V1.0

Connection



OSD Functions



Operating Instructions: 1. Connect the menu board to the movement

3. Press the center button, the operation interface will pop up, the operation interface is divided into four lines, the first line and the second line is to provide a choice of characters, the third line is to

2. Wait for the movement to power on the picture

- delete the option, the fourth line is the current character, the black background is the current cursor position 4. Press up, down, left or right to move the cursor in the character line, and press center to select the character to be inserted into the current string. 5. move the cursor to DEL, press the center, you can delete the last character in the string, all clear
- the current string will become [NA], this time that there is no character 6. Move the cursor to the fourth line of the current character line, press the center key to exit the operation. This is the string if not empty, the lower left corner will have the current settings string
- **Serial Communication Description**

TX Master transmit, 3.3V level, baud rate default 115200bps **RX** Master receive, 3.3V level, baud rate default 115200bps

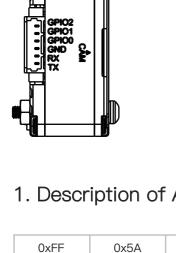
version

(1Byte)

header (10Byte)

cmd

(2Byte)



(1Byte)

GND	Reference Ground				
GPIO0	General Purpose IO, 3.3V level				
GPIO1	General Purpose IO, 3.3V level				
GPIO2	General Purpose IO, 3.3V level				
Agreement					

payload_len

(4Byte)

payload

crc16

(2Byte)

1.1 Field Description
OxFF: constant value

sub_cmd

(1Byte)

sub_cmd: subcommand payload_len: Payload data length

0x5A: constant value

cmd: Command id

(1Byte)

payload: Data content

while(length--)

crc ^= *data++; for (i = 0; i < 8; ++i)

if (crc & 1)

crc16: Checksum value with header and payload

version: Protocol version (initial version 0)

1.2 Calibration Function crc16_code static uint16_t crc16_modbus(uint8_t *data, uint32_t length) uint8_t i; uint16_t crc = 0xffff; // Initial value

 $crc = (crc >> 1) ^ 0xA001; // 0xA001 = reverse 0x8005$ else crc = (crc >> 1);return crc; 2. Command Definition host → dev: The host computer sends to the device dev→host: The device sends to the host computer 2.1 Getting the Version

sub_cmd

0

0

payload_len

(Byte)

0

Ν

Instruction

Returns the firmware

version string

Instruction

1Byte brightness value (0–100), no payload without setting only return the actual brightness value

Returns the current brightness value

Set the pseudo-color serial number,

0 is off pseudo-color

Instruction

Close Hot Tracking

Open Hot Tracking

// crc ^= *data; data++;

2.2 Image Adjustment

1

1

cmd

0

0

sub_cmd

0

0

0

sub_cmd

0

1

Directional

host->dev

dev->host

Directional cmd

host->dev

dev->host

host->dev	1	1	1/0	1Byte contrast value (0-100), no payload not set only return the actual contrast value
dev->host	1	1	1	Returns the current contrast value
2.3 Pseud	o–Co	olor		
Directional	cmd	sub_cmd	payload_len (Byte)	Instruction

1

payload_len

(Byte)

1/0

1

host->dev 2.4 Shutter Control

2

Directional	cmd	sub_cmd	payload_len (Byte)	Instruction
host->dev	3	0	1	Manual shutter calibration image
host->dev	3	1	1	Disable automatic shutter calibration
host->dev	3	2	1	Enable automatic shutter calibration

payload_len

(Byte)

1

1

host->dev 4

Enable Auto Shutter

2.5 Hot Tracking

cmd

4

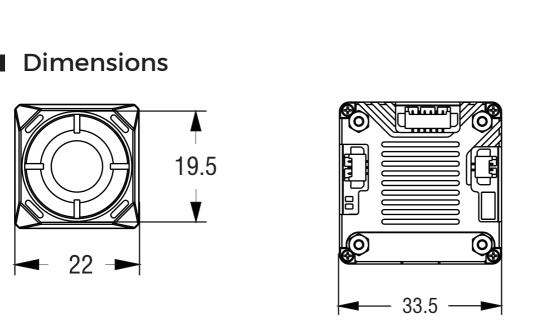
3. Example of Command

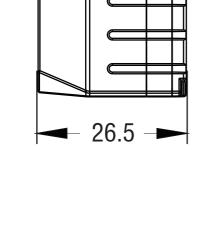
Directional

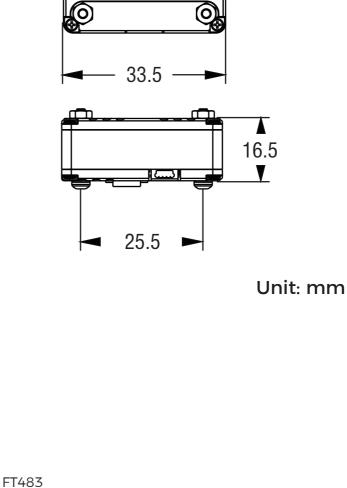
host->dev

Command Description	Command Data			
Get version	FF 5A 00 00 00 00 00 00 00 C7 57			
Set the contrast to 80%	FF 5A 00 01 00 01 01 00 00 00 50 EB 73			
Set the contrast to 50%	FF 5A 00 01 00 01 01 00 00 00 32 6A 9A			
Set the brightness to 80%	FF 5A 00 01 00 00 01 00 00 00 50 EA A2			
Set the brightness to 50%	FF 5A 00 01 00 00 01 00 00 00 32 6B 4B			
Set pseudo color 5	FF 5A 00 02 00 00 01 00 00 00 05 6A 88			
Set pseudo color 0	FF 5A 00 02 00 00 01 00 00 00 00 AA 8B			
Shutter Calibration	FF 5A 00 03 00 00 00 00 00 F4 57			
Disable Auto Shutter	FF 5A 00 03 00 01 00 00 00 00 C9 97			

FF 5A 00 03 00 02 00 00 00 00 8D 97







Specifications Model

Sensor Resolution

LENS FOV Frame Rate **Power Consumption** Output Supply Voltage Temperature Interface Latency Image Quality

F1.0/9.1mm 48°(H)*34°(V)*59°(D) 25/50fps <1.5w PAL 9V~24V -20°C~60°C Analog Interface: CVBS Average Latency 20ms

Allmage Enhancement

Uncooled Vanadium Oxide

400x300